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**Technical innovation benefits the world**  
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**RENLE**

RNB6000 SERIES  
FREQUENCY INVERTER



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## About RENLE

Shanghai RENLE Science & Technology Co., Ltd. is one large industrial enterprise for capital operation, brand operation, and industry operation and so on. RENLE is specialized in the production of LV/MV/HV motor soft starter, LV/MV/HV frequency converter, intelligent electric equipment, new energy electric equipment and complete sets of LV/HV transmission and distribution equipments.

## National key projects

Expo 2010 Shanghai China, 2008 Beijing Olympic Games, Yangshan Deepwater Port Project of Shanghai International Shipping Center, Shanghai Pudong Airport, Shanghai Hongqiao Airport, the Three Gorges Project, Gansu Satellite Launching Center, South-to-North Water Diversion Project, West-to-East Natural Gas Transmission Project, China National Petroleum Corp. and SINOPEC etc.

## Manufacturer of intelligent power grid and new energy electric

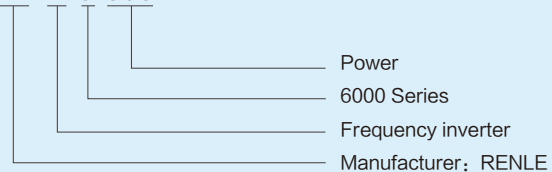


## RNB6000 SERIES FREQUENCY INVERTER



### ● Type introduction:

#### RN-B-6-000



### ● Note:

The brake unit and DC reactor are both external configuration as optional accessories.

### ● The relation between the altitude and the output derating

| Altitude (meter) | Output current derating rate |
|------------------|------------------------------|
| Below 1000       | 1.00                         |
| 1000 – 1500      | 0.97                         |
| 1500 – 2000      | 0.95                         |
| 2000 – 2500      | 0.91                         |
| 2500 – 3000      | 0.88                         |

## ● Unique product performance

### **Newest space vector technology**

Excellent vector algorithm guarantees the big torque for low frequency in premise of lowest switch loss. High efficiency power voltage availability and optimized sine wave output will reduce its working noise and heat of motor.

### **Unique software dead-zone compensation**

Dead-zone time is the cause of low frequency pulsation torque. RNB6000 unique software dead-zone compensation guarantees stable torque characteristics with low frequency and extremely low speed.

### **Excellent speed tracking self-starting without speed sensor**

Start the running motor to guarantee the user's equipment to keep stable running. RNB6000 can automatically recognize the speed to realize stable speed tracking.

### **Automatic energy saving running**

Unique software power factor regulation which will regulate the power factor dynamically according to the change of load so as to save much energy.

### **Voltage fluctuation control**

Automatic voltage control (AVC) could guarantee the output voltage vibration is within  $\pm 5\%$  when the input voltage vibration is within  $\pm 20\%$ .

### **Complete protection function**

Overvoltage, overcurrent, undervoltage, IGBT short-circuit, inverse time limit overload protecting design. And it can realize safe protection under short-circuit load and grounding.

### **DC power supply**

Save the power supply investment.

### **Built-in flexible PWM energy consumption braking.**

The user selects the suitable braking resistor to realize energy consumption braking conveniently.

### **Friendly HMI and flexible input & output interface port**

LCD Chinese-English display, supply 7 routines digital input, 2 routines analog output, 3 routines digital output, and multi-speed programmable running.

### **Intelligent temperature detection and fan management**

#### **DC braking**

#### **Power loss ride-through**

## ● Detailed specification

| Serial No. | Type    | Rate current | Rated voltage | General application |                        | Heavy load application |                        | The calculated total power loss (W) |
|------------|---------|--------------|---------------|---------------------|------------------------|------------------------|------------------------|-------------------------------------|
|            |         |              |               | Rate current        | Applicable motor power | Rate current           | Applicable motor power |                                     |
| 1          | RNB6001 | 4.1          | ~ 380         | 4.1                 | 1.5                    | 3.2                    | 1.1                    | 52                                  |
| 2          | RNB6002 | 5.6          |               | 5.6                 | 2.2                    | 4.1                    | 1.5                    | 67                                  |
| 3          | RNB6003 | 7.2          |               | 7.2                 | 3.0                    | 5.6                    | 1.5                    | 81                                  |
| 4          | RNB6004 | 10.0         |               | 10.0                | 4.0                    | 7.2                    | 2.2                    | 103                                 |
| 5          | RNB6005 | 13.0         |               | 13.0                | 5.5                    | 10.0                   | 4.0                    | 142                                 |
| 6          | RNB6007 | 16.0         |               | 16.0                | 7.5                    | 13.0                   | 5.5                    | 204                                 |
| 7          | RNB6011 | 24.0         |               | 24.0                | 11                     | 16.0                   | 7.5                    | 295                                 |
| 8          | RNB6015 | 32.0         |               | 32.0                | 15                     | 24.0                   | 11                     | 450                                 |
| 9          | RNB6018 | 37.5         |               | 37.5                | 18.5                   | 32.0                   | 15                     | 540                                 |
| 10         | RNB6022 | 44.0         |               | 44.0                | 22                     | 37.5                   | 18.5                   | 660                                 |
| 11         | RNB6030 | 61.0         |               | 61.0                | 30                     | 44.0                   | 22                     | 900                                 |
| 12         | RNB6037 | 73.0         |               | 73.0                | 37                     | 61.0                   | 30                     | 1100                                |
| 13         | RNB6045 | 90.0         |               | 90.0                | 45                     | 73.0                   | 37                     | 1350                                |
| 14         | RNB6055 | 106          |               | 106                 | 55                     | 90.0                   | 45                     | 1650                                |
| 15         | RNB6075 | 147          |               | 147                 | 75                     | 106                    | 55                     | 2250                                |
| 16         | RNB6090 | 177          |               | 177                 | 90                     | 147                    | 75                     | 2700                                |
| 17         | RNB6110 | 212          |               | 212                 | 110                    | 177                    | 90                     | 3300                                |
| 18         | RNB6132 | 260          |               | 260                 | 131                    | 212                    | 110                    | 3960                                |
| 19         | RNB6160 | 315          |               | 315                 | 160                    | 260                    | 132                    | 4800                                |
| 20         | RNB6200 | 368          |               | 368                 | 200                    | 315                    | 160                    | 6000                                |
| 21         | RNB6250 | 480          |               | 480                 | 250                    | 368                    | 200                    | 7500                                |
| 22         | RNB6315 | 600          |               | 600                 | 315                    | 480                    | 250                    | 9450                                |
| 23         | RNB6400 | 760          |               | 760                 | 400                    | 600                    | 315                    | 12000                               |
| 24         | RNB6500 | 972          |               | 972                 | 500                    | 760                    | 400                    | 15000                               |

## ● Product technical specification

|        | Item                            | Standard  |
|--------|---------------------------------|---|
| Input  | Power supply                    | 3 phase 380V 50/60Hz  |
|        | input voltage range             | Voltage: $\pm 20\%$ , Voltage imbalance ratio: $< 3\%$ ; Frequency: $\pm 5\%$   |
| Output | Applicable motor capacity       | 1.5~315kW ( Constant torque application )   |
|        | Rated current output            | 4.0~600A ( Constant torque application )  |
|        | Rated voltage                   | 3 phase 380V 50/60Hz  |
|        | frequency range                 | 0 ~ 600Hz   |
|        | Setting resolution              | <ul style="list-style-type: none"> <li>Analog setting: 0.4% of the maximum setting frequency</li> <li>Digital setting: 0.01Hz ( below 100Hz ); 0.1Hz ( above 100Hz )</li> </ul>   |
|        | Frequency precision             | <ul style="list-style-type: none"> <li>Analog setting: <math>\pm 0.2\%</math> ( <math>25 \pm 10^\circ\text{C}</math> )</li> <li>Digital setting: <math>\pm 0.01\%</math> ( <math>-10 \sim +50^\circ\text{C}</math> )</li> </ul> |
|        | Over current withstand capacity | 150% rated output current for 1 Min.  |



|                    |  |   |
|--------------------|--|---|
| <b>Control</b>     | Control type                                 | Optimized space vector SPWM   |
|                    | Torque compensation                          | Automatic torque arising for starting, which will reach 150%  |
|                    | Slip compensation                            | Compensate the speed drop when driving the load in order to enhance the mechanical characteristic hardness  |
|                    | Restarting when instant power supply failure | It can restart when the power recovers after momentary outage   |
|                    | Upper and lower frequency                    | Set the upper frequency and lower frequency   |
|                    | Skip frequency                               | Set 3 groups of skip frequency  |
|                    | Speed tracking restarting                    | The running motor can change to variable frequency in operation with no need to stop  |
|                    | Acceleration and deceleration time           | 0.1 ~ 999.9sec, time for acceleration and deceleration can be set independently   |
|                    | Acceleration and deceleration integral type  | The available linear line, S1 and S2 curve, which will satisfy multi-purpose demand   |
|                    | Running operation mode                       | Keyboard operation; keyboard control; communication operation; digital input operation and analog input control<br>Serial communication: controlled by upper machine through the RS485 port   |
|                    | Stop mode                                    | Free stop, deceleration stop and deceleration with DC braking stop  |
|                    | Low noise running control                    | Adjust the frequency from 1KHz to 6KHz to reduce the running noise.   |
|                    | PID closed-loop control                      | It is available application for different closed-loop control system such as flow, pressure, temperature  |
|                    | Frequency setting                            | <ul style="list-style-type: none"> <li>Keyboard setting: use ▲ and ▼ keys to set.</li> <li>Analog input signal setting(potential setting): with 0 ~ 10VDC voltage signal, 0 ~ 20mA, 4~20mA current signal setting</li> <li>Multi-step frequency selection setting: Configured by the digital input to select the 1 ~ 7 running frequency</li> </ul> |
|                    | Running status output signal                 | <ul style="list-style-type: none"> <li>Relay output: running status, fault status and monitoring status are available.</li> <li>Analogue output: available to select related parameters like frequency, current, voltage, speed and so on.</li> </ul>   |
| <b>Display</b>     | Running/stop                                 | Display frequency, current and so on  |
|                    | Setting mode                                 | Display the set menu No. or set parameter value   |
|                    | Function operation mode                      | Display the operating function information and warning information.   |
|                    | Alarm and fault mode                         | Display all the alarms and fault codes  |
| <b>Protection</b>  | Overload protection                          | Monitor the output load current of frequency inverter to protect the frequency inverter.  |
|                    | Overvoltage protection                       | Monitor the overvoltage of DC bus to protect the frequency inverter.  |
|                    | Surge voltage protection                     | When power line-to-line or line-to-grounding exists the surge voltage, this function will protect the frequency inverter  |
|                    | Under voltage protection                     | Monitor the fall of DC bus voltage, when the voltage is lower than the setting level of n608, it can protect the frequency inverter   |
|                    | Overheat protection                          | Monitor the temperature increment of the heat sink. Once the temperature exceeds the setting, this function will protect the frequency inverter   |
|                    | Short-circuit protection                     | Short-circuit or overcurrent of frequency output side, this protection will protect frequency inverter.   |
|                    | Short-circuit to grounding protection        | When Short-circuit to grounding happens on output side of frequency inverter, this function will protect frequency inverter   |
|                    | Motor overheat protection                    | The frequency inverter will use electronic relay to carry out the motor overload protection   |
|                    | Over current protection                      | 100 ~ 150%(Adjustable)  |
|                    | Grounding protection                         | The frequency inverter will stop when the current is more than 80%Ie  |
| <b>Environment</b> | Application site                             | <ul style="list-style-type: none"> <li>Indoor, the altitude is less than 1000m. It requests no corrosive gas, no flammable gas, no dust, no oil mist, no water drop. Prohibit direct sunshine without strong magnetic field interference</li> </ul>   |
|                    | Application temperature                      | -10℃ ~ 40℃  |
|                    | Application humidity                         | 5~95%RH ( No frost )  |
|                    | Vibration                                    | ≤0.5g   |
|                    | Storage temperature                          | -25℃ ~ +65℃   |

## ● Terminal function

### Function description of control terminal

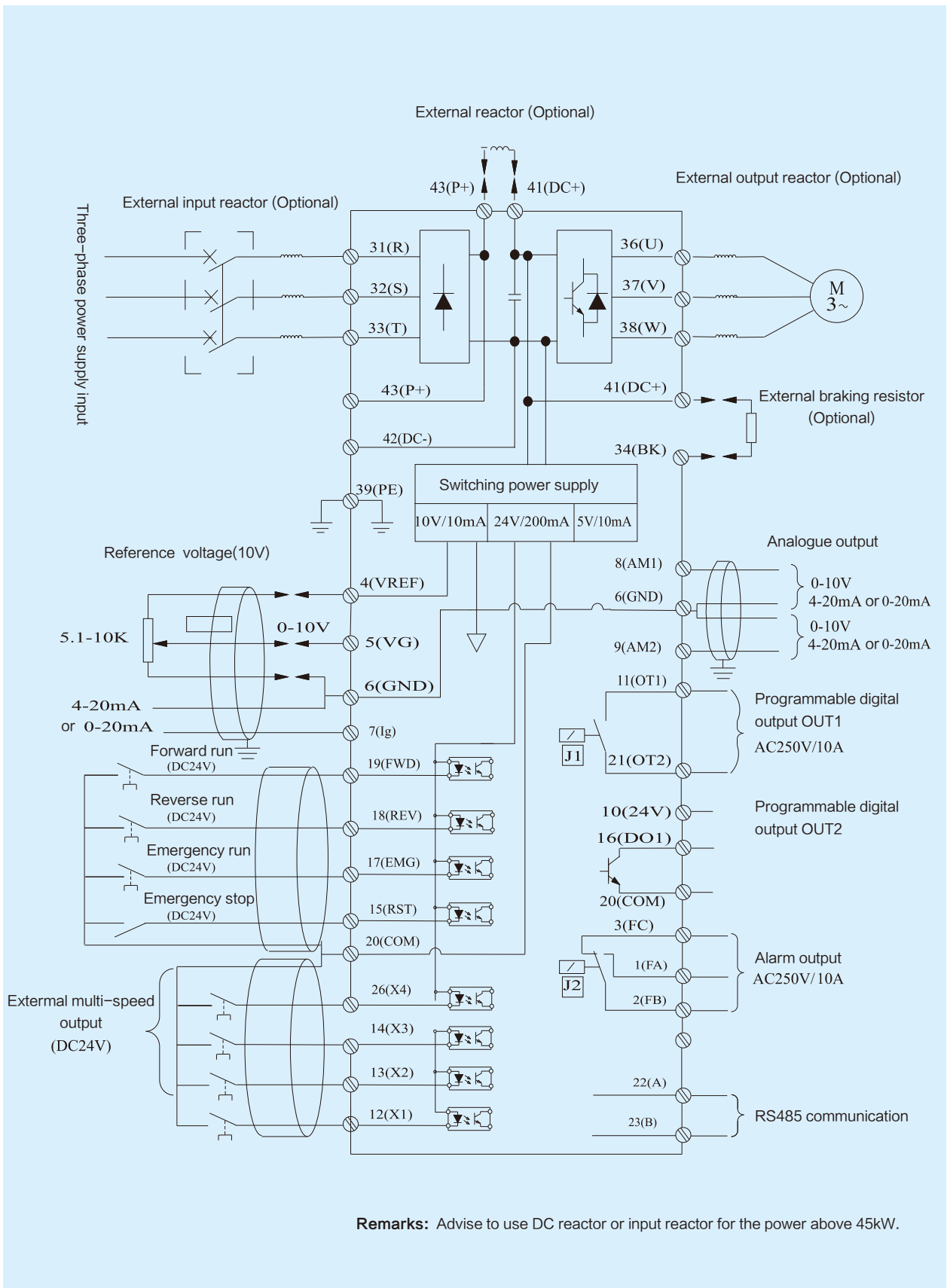
| Terminal Code        |                      | Terminal name                      | Instruction  |
|----------------------|----------------------|------------------------------------|--|
| 4                    | VREF                 | Power supply for potential meter   | Power supply(+10VDC) of frequency setting potential meter(5–10k)   |
| 5                    | VG                   | Voltage input of frequency setting | (1) Connect the external analog input voltage command to set the frequency 0–10V/ 0–100% resolution 10bit input precision is 1%<br>(2) input the feedback signal of PID control (input resistor 20K)   |
| 7                    | IG                   | Current input of frequency setting | (1) Connect the external current to set frequency 4–20mA (or 0–20mA)/0–100%<br>(2) input the feedback signal of PID control, resolution of 10bit input precision is 1% (input resistor 250Ω)   |
| 6                    | GND                  | Digital/Analog signal common       | The common terminal of analog input/output signal  |
| 12<br>13<br>14<br>26 | X1<br>X2<br>X3<br>X4 | External multi-purpose terminal    | (1) 12、13、14 connect with 20 to form external 7 steps setting frequency. (See the detailed instruction)<br>(2) X1、X2 JOG potential meter<br>(3) Extension function(See the detailed instruction)   |
| 15                   | RST                  | Reset                              | 15 connects with 20 to reset the frequency inverter  |
| 17                   | EMG                  | Emergency stop                     | 17 connects with 20 to make the motor stop freely, the electric level is 24VDC   |
| 18                   | REV                  | Reverse                            | REV–COM close(ON), reverse running, open(OFF), deceleration to stop  |
| 19                   | FWD                  | Forward                            | FWD–COM (ON), (Forward running), (OFF), deceleration to stop   |
| 20                   | COM                  | Control signal common              |  |
| 10                   | 24V                  | Control signal power               | Available to be offered by the external power(24VDC, current <200mA)   |
| 8                    | AM1                  | Analog output                      | Output current, voltage and frequency signal (GND is common terminal) terminal output level is 0– V electric level   |
| 9                    | AM                   |                                    | Output current, voltage and frequency signal (GND is common terminal) terminal output signal is 4–20mA(or 0 – 20mA)  |
| 11<br>21             | OT1<br>OT2           | Programmable output                | Output relay signal of the start/stop, reaching the given frequency(open – loop), exceeding preset frequency, less than preset frequency, the contact capacity: AC 250V A  |
| 16                   | DO1                  | Programmable output                | Output the signal of the start/stop, reaching the given frequency(open–loop), exceeding preset frequency, less than preset frequency, open collector signal output, electrical level 24 VDC, current < 100mA. Voltage withstand 50V  |
| 22<br>23             | A<br>B               | Signal output                      | RS485 communication  |
| 1<br>2<br>3          | FA<br>FB<br>FC       | Fault relay output                 | When the frequency inverter stops because of alarm caused by overcurrent, over voltage, undervoltage, overheat, overload, short-circuit. The fault relay output contact (1.2.3) will output the alarm signal. If the alarms occur, the alarms need to be reset according to the manual.Contact capacity: AC250V10A |

## ● System control function

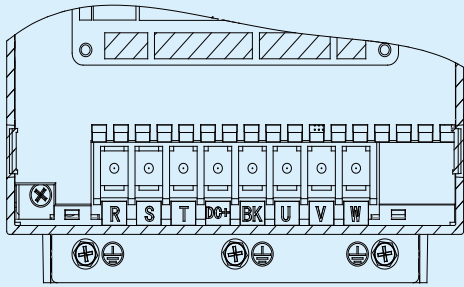
| Input control   | output control  |
|---|---|
| <ul style="list-style-type: none"> <li>Analog input:           <ul style="list-style-type: none"> <li>Voltage input: ( 0 – 10V ) 1 loop</li> <li>Current input: 4 ~ 20mA or 0 ~ 20mA 1loop</li> </ul> </li> <li>Digital input: 8 loops           <ul style="list-style-type: none"> <li>1 loop for Forward, 1 loop for reverse, 1 loop for emergency stop and 1 loop for reset</li> <li>Programmable point: 4 loops (See the function table)</li> </ul> </li> </ul> | <ul style="list-style-type: none"> <li>Analog output: Two loops (Programmable output) (See function table)           <ul style="list-style-type: none"> <li>0 ~ 10VOutput</li> <li>4 ~ 20mA or 0 ~ 20mA output</li> <li>2 loops programmable terminal can output the voltage, current, power and frequency.</li> </ul> </li> <li>digital output: 3 loops           <ul style="list-style-type: none"> <li>Fault output relay: 1 loop (see function table)</li> <li>Programmable digital output: 2 loops (See function table)</li> </ul> </li> </ul> |



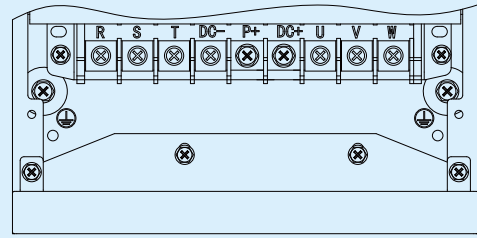
## ● Wiring diagram



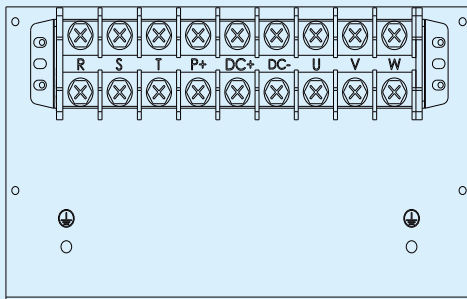
● Diagrammatic sketch for main circuit terminal



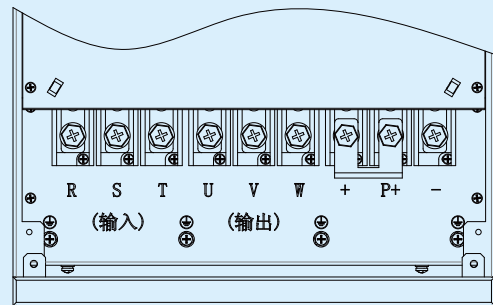
Below 11kW



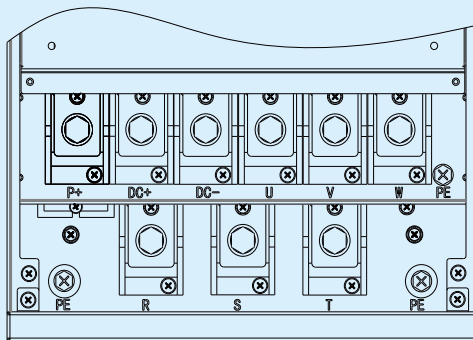
15-37kW



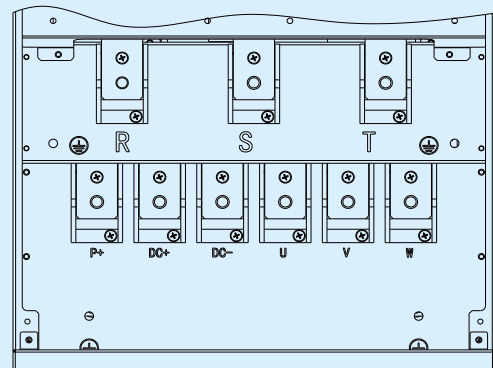
45-55kW



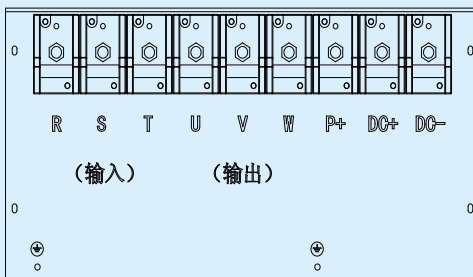
75-90kW



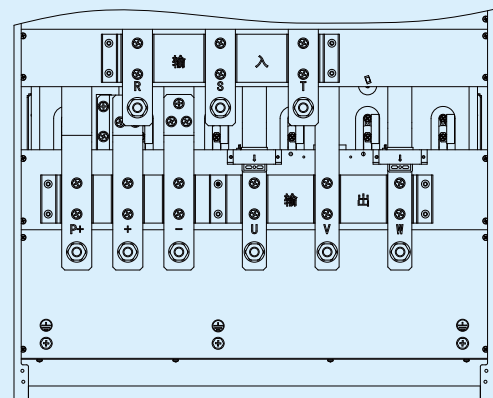
110-132kW



160-200kW



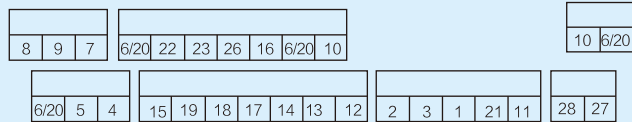
250-315kW



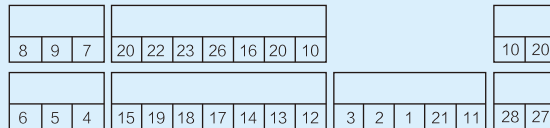
400-500kW

## ● Wiring terminal layout

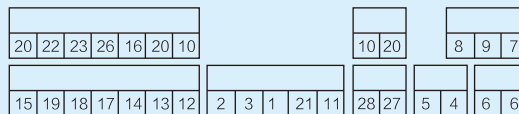
- 1) Applicable power section:  
1.5 ~ 11kW



- 2) Applicable power section:  
15 ~ 55kW

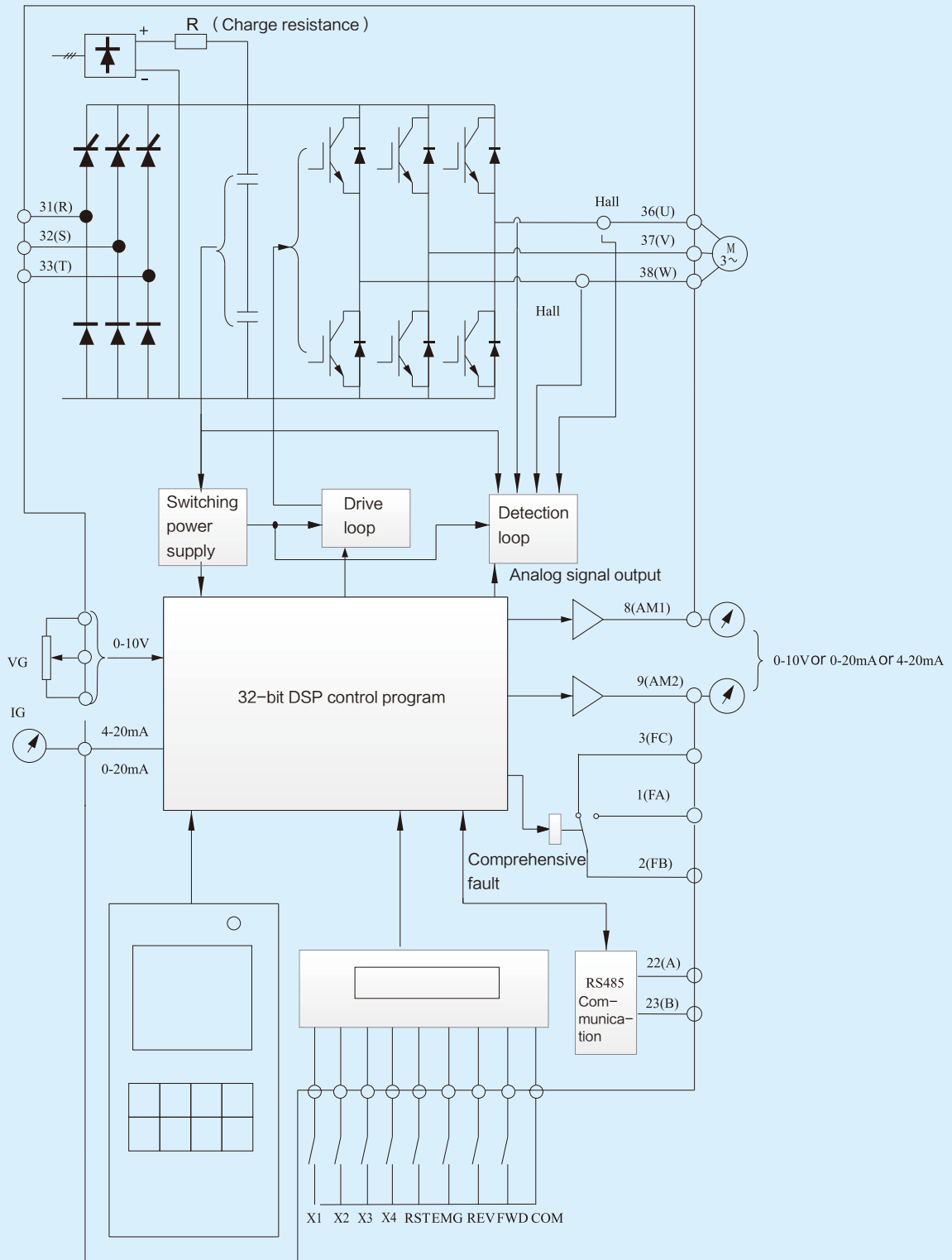


- 3) Applicable power section:  
75 ~ 500kW

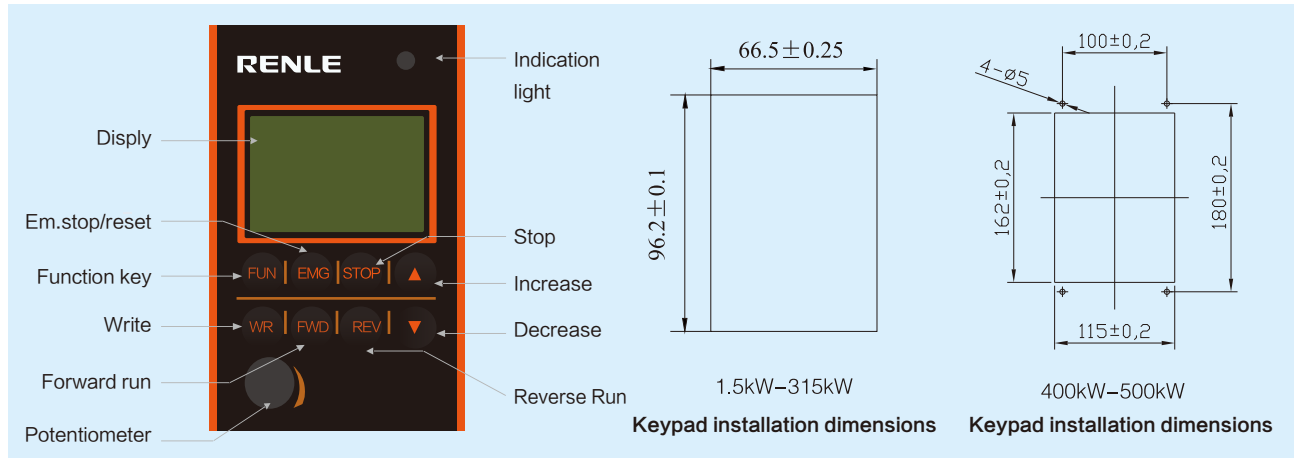


| Terminal Code |      | Terminal Name                      |
|---------------|------|------------------------------------|
| 1             | FA   | Fault relay output                 |
| 2             | FB   |                                    |
| 3             | FC   |                                    |
| 4             | VRBF | Power supply for potential meter   |
| 5             | VG   | Voltage input of frequency setting |
| 6             | GND  | Digital / Analog signal common     |
| 7             | Ig   | Current input of frequency setting |
| 8             | AM1  | Analog output                      |
| 9             | AM2  |                                    |
| 10            | 24V  | Control signal power               |
| 11            | OT1  | Programmable OUT1                  |
| 21            | OT2  | External multi-purpose terminal    |
| 12            | X1   |                                    |
| 13            | X2   |                                    |
| 14            | X3   |                                    |
| 26            | X4   |                                    |
| 15            | RST  | Reset                              |
| 16            | D01  | Programmable OUT2                  |
| 17            | EMG  | Emergency stop                     |
| 18            | REV  | Reverse                            |
| 19            | FWD  | Forward                            |
| 20            | COM  | Control signal common              |
| 22            | A    | RS485 Signal output                |
| 23            | B    |                                    |

● Internal schematic diagram



## ● Operation keyboard



The keyboard panel can display English and Chinese. The keyboard panel has abundant functions, such as the keyboard panel running (frequency setting, running/stop command), function code data confirmation and change with many confirmation functions. Please operate the equipment after understanding the function operation completely.

- Indication lamp: Indicate the frequency inverter status.
  - a. Green lamp flashing: indicate that the inverter is forward running;
  - b. Red lamp flashing: indicate that the inverter is reverse running
  - c. Alternating flashing between red lamp and green lamp: Indicate the fault happens in frequency inverter
- Display: LCD display is used to display frequency, motor current, DC voltage, synchronous speed, temperature and so on. And it also displays the reason of stop because of protection activation. Moreover, It displays function codes and data codes set by the program.
- Stop key: it is used to interchange main monitoring value display under the status of regular motor stop or stop status.
- Value increased key: it is used to search for the function code or modify the parameters (To constantly press this key will make it to be with automatic step-distance recognition function)
- Value decreased key: It is used to search for the function code or modify the parameters (To constantly press this key will make it to be with automatic step-distance recognition function)
- Emergency stop/reset key: It is used to stop freely and reset fault .
- Function key: It is used for transferring window between function code and function parameter. Pressing the key for one time will transfer one time.
- Input key: It is used to confirm (store) parameter or interchange the display of main monitoring value under running state.

## Note Item:

When the frequency inverter is controlled by the contactor or use the output relay of the frequency inverter to control the contactor, the R-C damping loop should be connected with the loop of AC contactor. The DC contactor should be added with the fly-wheel diode.

### Note:

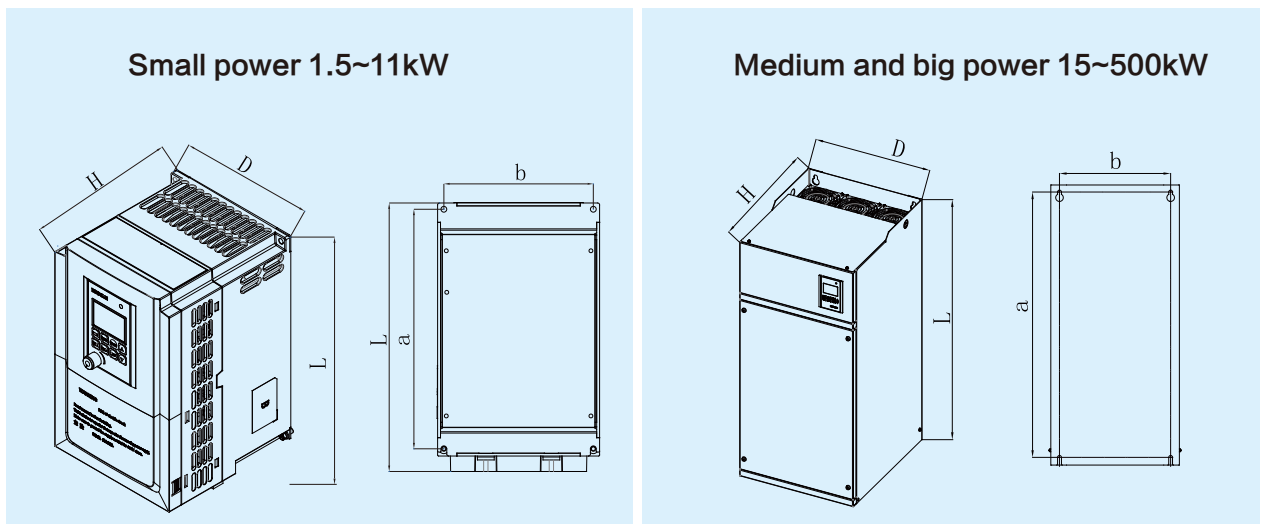
Please confirm that the input power phase number of frequency inverter, rated input voltage should comply with phase and voltage value of AC power number. The frequency inverter just needs three phase AC power supply. The zero wire can not be wired into frequency inverter in any way.

### Note:

- Must connect the grounding wire
- The wiring operation should be carried out by the qualified personnel.
- Confirm to cut off the power and then begin to operate.
- When there is the thermal relay between frequency inverter and motor, we should connect the output filter, input reactor and output reactor due to the wrong action which probably happen even if the cable length from frequency inverter to motor is less than 50m.

|                                |   |
|--------------------------------|---|
| <b>Input reactor (option)</b>  | <p>The input reactor can repress the high order harmonic of the frequency inverter current so as to improve the input power factor and prevent the surge impact. For following situation, the input AC reactor is suggested to be used.</p> <ol style="list-style-type: none"> <li>1.Imbalance of three phases is more than 3%.</li> <li>2.The SCR equipments or the power factor compensation device controlled by the switch on the same power supply.</li> <li>3.The power of frequency inverter is above 110KW</li> </ol> |
| <b>Output reactor (option)</b> | <p>The main function of output reactor is to compensate the influence of the distributed capacitor, which could repress the output harmonic of frequency inverter and reduce the noise of frequency inverter. For following situation, we must adopt output reactor.</p> <ol style="list-style-type: none"> <li>1.The length of cable to motor: below 11kw, more than 50m; above 15kw, more than 100m.</li> </ol>   |
| <b>DC reactor (option)</b>     | <p>Function: improve the power factor. If the power is above 45KW (including 45kw), the DC reactor is suggested to be used.</p>   |

● **Size of outline and installation**



| 6000 series | (L) mm | (D) mm | (H) mm | Installation size (a × b) | Screw installation |
|-------------|--------|--------|--------|---------------------------|--------------------|
| 1.5-5.5kW   | 202    | 142    | 178    | 177×129                   | M5                 |
| 7.5-11 kW   | 278    | 168    | 183    | 248×155                   | M5                 |
| 15-22 kW    | 508    | 242    | 245    | 480×180                   | M8                 |
| 30-37 kW    | 580    | 242    | 245    | 560×180                   | M8                 |
| 45-55 kW    | 655    | 307    | 288    | 630×220                   | M8                 |
| 75-90 kW    | 709    | 370    | 295    | 692×260                   | M8                 |
| 110-132 kW  | 800    | 370    | 430    | 760×320                   | M10                |
| 160-200 kW  | 930    | 468    | 405    | 900×380                   | M10                |
| 250-315 kW  | 1170   | 620    | 418    | 1140×520                  | M10                |
| 400-500 kW  | 1430   | 800    | 498    | 1398×680                  | M12                |

Remarks: \* for wall mounting in installation.





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## National Key Projects



- Three Gorges Project
- Beijing Olympic Rowing-Canoeing Park
- Beijing Olympic Games Supporting Projects
- Beijing Wukesong Gymnasium
- Government Offices Administration of the State Council
- CCTV, China
- Beijing Capital International Airport
- South-to-North Water Diversion Project
- Huangshan-Quzhou-Nanping Expressway
- West-to-East Electricity Transmission Project
- West-to-East Natural Gas Transmission Project
- Stations of Shanghai Magnetic Levitation Rail Transportation
- Expo 2010 Shanghai China Supporting Projects
- Shanghai Pudong Airport
- Shanghai International Automobile Museum
- Shanghai Hongqiao Airport Extension Project
- Terminal of Inner Mongolian Hohhot Baita International Airport Extension Project
- Shenyang Olympic Center
- Qingdao Olympic Center
- Jinan Olympic Center
- Chengdu Shuangliu International Airport Extension Project
- Chongqing Yuanjiagang Olympic Sports Center
- Guangzhou New Baiyun International Airport
- Wuhan Tianhe Airport
- Shanghai Metro Line 3
- Chongqing International Convention & Exhibition Center
- Shanxi Wanjiashai Yellow River Diversion Project
- Qinghai Xiaoyou Mountain Ecological Engineering
- Tianjin Eight Large Regions Heating Engineering
- Shandong Heze City Yellow River Diversion Project
- Yangshan Deepwater Port Project of Shanghai International Shipping Center
- Sichuan Xichang Satellite Launching Center
- Guangxi Longtan Hydroelectric Project

Gansu Satellite Launching Center  
Yunnan Honghe River Nansha Hydropower Station  
Datang International Power Generation Co., Ltd.  
Guizhou Kailin (Group) Co., Ltd  
Inner Mongolian Shenhua Group Corporation Limited  
Shanghai Petrochemical Company Limited  
Baosteel Group Corporation in Shanghai  
Taizhou Petrochemical Co., LTD  
Anshan Iron and Steel Group Corporation  
Jilin Petrochemical Company  
Wuhan Iron and Steel (Group) Corp.  
Liuzhou Chemical Industry Co., Ltd, Guangxi  
Beijing Shougang Company Limited  
SINOPEC Cangzhou Company  
China Great Wall Aluminum Corporation  
SINOPEC Luoyang Company  
Guangxi Pingguo Aluminium Company  
Yueyang Petrochemical Factory  
Liuzhou Iron and Steel Co., Ltd  
Sinopec Nanjing Chemical Industry Co., Ltd  
Magang (Group) Holding Company Ltd  
SINOPEC Beijing Yanshan Company  
Shanxi Zhongyang Iron and Steel Co., Ltd.  
PetroChina Urumqi Petrochemical Company  
Daqing Oilfield Limited Company  
PetroChinaJinxi Petrochemical Company  
SINOPEC Shenli Oilfield  
CNPC Dushanzi Petrochemical Company  
PetroChinaLiaohe Oilfield  
Beijing Financial Street  
PetroChinaTarim Oilfield  
Panda Museum of Chengdu Panda Ecological Park  
Karamay Oilfield  
Qingdao Beihai Shipyard  
PetroChinaChangqing oilfield

